



Left Position:

1-3 Closed

4-5 Closed

1 2 3 4 5



Center Position:

1-2 Closed

4-5 Closed

1 2 3 4 5



Right Position:

1-2 Closed

3-5 Closed

1 2 3 4 5



1: Out to Motor

2: -12VDC Input

3: +12VDC Input

4: Jumper to #2

5: Out to Motor